

# A New Explicit Finite Free Resolution of Ideals Generated by Monomials in an $R$ -sequence

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Juliann Geraci

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University of Nebraska - Lincoln

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$$\dots A_2 \xrightarrow{d_2 = \begin{pmatrix} \text{relations on} \\ \text{the relations} \\ \text{in } d_1 \end{pmatrix}} A_1 \xrightarrow{d_1 = \begin{pmatrix} \text{relations on the} \\ \text{generators of } M \end{pmatrix}} A_0 \xrightarrow{\begin{pmatrix} \text{generators} \\ \text{of } M \end{pmatrix}} M \rightarrow 0$$

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  - Hilbert series
  - Betti Numbers
  - Ext, Tor and Hom functors

# Preliminary Definitions

Let  $A, B, C$  be  $R$ -modules.

## Definition

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A sequence  $\dots A_{n-1} \rightarrow A_n \rightarrow A_{n+1} \dots$  of homomorphisms is said to be an **exact sequence** if it is exact at every  $A_n$  between a pair of homomorphisms.

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## Definition

Given a module  $M$  over a ring  $R$ , a **free resolution** of  $M$  is an exact sequence of free  $R$ -modules

$$\dots \xrightarrow{d_{n+1}} A_n \xrightarrow{d_n} \dots \xrightarrow{d_2} A_1 \xrightarrow{d_1} A_0 \xrightarrow{\varepsilon} M \rightarrow 0$$

where  $d_i$  are homomorphisms called **differentials** and  $\varepsilon$  is called the **augmentation map**



# Finding a (close to) Minimal Resolution

The best case scenario: construct a minimal free resolution.

- A free resolution is minimal if and only if at each step we make an optimal choice, that is, we choose a minimal system of generators of the kernel in order to construct the next differential.
- A minimal free resolution is smallest in the sense that it lies (as a direct summand) inside any other free resolution of the module.

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Two particularly "nice" resolutions that are close to minimal

- Taylor Resolution
- Lyubeznik Resolution

# Preamble

Let  $K$  be a field and let  $R = K[x_0, \dots, x_n]$ .

Let  $y_1, \dots, y_m$  be  $m$  monomials in the  $x_i$ , with  $\mathcal{I} = (y_1, \dots, y_m)$ , an ideal of  $R$ .

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Some examples of monomial ideals;

- For  $R = \mathbb{C}[x, y, z]$ 
  - $(x, y, z)$
  - $(xy, z^2)$
  - $(x^y z^3, x)$

# The Taylor Resolution

The **Taylor Resolution** of  $R/\mathcal{I}$  is given as

$$0 \rightarrow R^{(m)} \rightarrow \dots \rightarrow R^{(s)} \rightarrow R^{(s-1)} \rightarrow \dots \rightarrow R^{(1)} \rightarrow R \rightarrow R/\mathcal{I} \rightarrow 0$$

The differential; for  $I = \{i_1, \dots, i_s\}$ ,

$$d(e_I) = \sum_{j=1}^{j=s} (-1)^{j+1} \frac{\text{lcm}(y_{i_1}, \dots, y_{i_s})}{\text{lcm}(y_{i_1}, \dots, \hat{y}_{i_j}, \dots, y_{i_s})} e_{I \setminus i_j}$$

# The Taylor Resolution

**Example:** Let  $R = K[a, b, c]$  and  $\mathcal{I} = (a^2, ab, b^3)$ . Then the Taylor resolution of  $R/\mathcal{I}$  is

$$0 \rightarrow R \xrightarrow{\begin{pmatrix} a \\ -1 \\ b^2 \end{pmatrix}} R^3 \xrightarrow{\begin{pmatrix} 0 & -b^3 & -b \\ -b^2 & 0 & a \\ a & a^2 & 0 \end{pmatrix}} R^3 \xrightarrow{(a^2 \quad ab \quad b^3)} R \rightarrow R/\mathcal{I} \rightarrow 0$$

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# The Lyubeznik Resolution

The **Lyubeznik Resolution** of  $R/\mathcal{I}$  is a subcomplex of the Taylor resolution, which is generated in homological degree  $s$  by the basis elements  $e_{i_1, \dots, i_s}$  ( $1 \leq i_1 < \dots < i_s \leq m$ ) such that for every  $t < s$ ,  $q < i_t$ :  $y_q \nmid \text{lcm}(y_{i_t}, \dots, y_{i_s})$ .

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The differential is the same as the Taylor resolution, as it is a subcomplex. For  $I = \{i_1, \dots, i_s\}$ ,

$$d(e_I) = \sum_{j=1}^{j=s} (-1)^{j+1} \frac{\text{lcm}(y_{i_1}, \dots, y_{i_s})}{\text{lcm}(y_{i_1}, \dots, \hat{y}_{i_j}, \dots, y_{i_s})} e_{I \setminus i_j}$$

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# Comparison

$$\mathbf{T} : 0 \rightarrow R \xrightarrow{\begin{pmatrix} a \\ -1 \\ b^2 \end{pmatrix}} R^3 \xrightarrow{\begin{pmatrix} 0 & -b^3 & -b \\ -b^2 & 0 & a \\ a & a^2 & 0 \end{pmatrix}} R^3 \xrightarrow{(a^2 \quad ab \quad b^3)} R \rightarrow R/\mathcal{I} \rightarrow 0$$

Rank; 8

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Could this be minimal?

# Comparison

Using Macaulay2, we can compute the minimal resolution.

```
i1 : R=QQ[a,b]
o1 = R
o1 : PolynomialRing
i2 : I=ideal(a^2,a*b,b^3)
o2 = ideal (a2, a*b, b3)
o2 : Ideal of R
i3 : C= res I
o3 = R1 ← R3 ← R2 ← 0
      0      1      2      3
o3 : ChainComplex
i4 : C.dd
o4 = 0 : R ←----- R3 : 1
      | a2 ab b3 |
      1 : R ←----- R2 : 2
      {2} | -b 0 |
      {2} | a -b2 |
      {3} | 0 a |
      2 : R ←----- 0 : 3
      0
o4 : ChainComplexMap
```

That's familiar!





# References and Acknowledgements

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